Steps to set up the Arduino Uno R3

1/ First of all, I have three pieces : Arduino Uno R3 , micro servo , breadboard small

2/ Connecting the ground in the servo to the negative in the breadboard

3/ Connecting between the negative line connected to the GND in Arduino

4/ Connecting between the power in the servo and the 5v in the Arduino

5/ Connecting between -9 in Arduino with the signal in Servo

6/ Code > Variables > Create Variable > Name the variable (position)

7/ From code > control > drop the counting function in the blank and choose (up) and from (for) choose the position and make it from 1 to 179

8/ From Code > Outputs > Dropping the servo rotate into the space inside the counting function > Choosing the number 9 > From the variables choosing the position and dropping it in to… degrees to become from 9 to the position degrees

9/ From Code > Variables > Drop the set into the space above the count function > From the set selection position

10/ From Code > Control > Select Wait > Drop Wait into the count function under Rotate Servo and make it 20 milliseconds

11/ From code > control > counting function > dropping the second counting function into the space under the first counting function > selecting (down) > and from (for) selecting the position > and making it from 179 to 1

12/ From Code > Outputs > Dropping the servo rotate into the space inside the second counting function > Choosing the number 9 > From the variables choosing the position and dropping it in to… degrees to become from 9 to the position degrees

13/ We are ready now

14/ Click on start simulation to see what happens

15/ We will see that it works

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From code > control > drop the counting function in the blank and choose above and from (for) choose the position and make it from 1 to 179